WARP PREPARATION EQUIPMENT

## CREEL

1. Type:

Stationary, Side to Side, Side to Side and Front to Back, Rotating
2. Number of beams:
$8,12,16,20,24,28,32$
3. Beam widths:
$1,800,2,000,2,200,2,400 \mathrm{~mm}$
4. Brakes:

Pneumatic band (5 to 20kg. per beam)
5. Tension control:
by load cell ( $\pm 1.0 \mathrm{GPE}$ )
6. Beam flange diameter:
$1,000,1,100,1,250 \mathrm{~mm}$
7. Beam type:

Euro gear or journal type

## SIZE BOX

8. Number of size boxes::

1 or 2 Vertical Exit DDDS
9. Working width:

1,800, 2,000, 2,200, 2,400mm
10. Draw Roll Assy. (tension controlled): Motor driven
11. \#1 Squeeze roll rubber covered:
2) rolls with anodized matt finish
12. Size Rock driven roll:
$230 \mathrm{~mm} \varnothing$ working width +200 mm
13. \#2 Squeeze roll rubber covered: $230 \mathrm{~mm} \varnothing$ uni-squeeze x working width $+200 \mathrm{~mm}$
14. Squeeze roll rubber coverings: 65 durometer
15. \#1 Squeeze roll loading: 0-20kN
16. \#2 Squeeze roll loading: $0-40 \mathrm{kN}$

## GENERAL SPECIFICATIONS:

GSSM-100-D SIZING MACHINE (DENIM)
17. Seal-less pan design:

Roll journals are above the size level which eliminate the need for shaft seals
18. Sheet exit:

Single or wet-split
19. Tension control:
by load cell rolls ( $\pm 1.0 \mathrm{GPE}$ )
20. Stretch:

Monitored to within $0.01 \%$ stretch
21. Pan capacity (Teflon coated): 180, 200, 220, 240 liters
22. Filtration:

Screen type
23. Size temperature control:

RTD/on-off steam valve
24. Size heating:
direct steam heating
25. Size level control:
by Over-flow weir
26. Size add-on:
by continuous calculation from size consumption and speed/yarn throughput, size add-on control using PLEVA (optional)
27. Storage kettle:

Closed steam coil, 1,200, 1,500, 2,000 liter
28. Cooking kettle:

Open steam coil, 1,000 liter
29. Kettle pumps:

From cooker to storage and storage to sizer
30. Controls

Temperature control for each kettle

## DRYING SECTION

31. Dry Cylinder specifications:
$800 \mathrm{~mm} \varnothing \times$ working width +200 mm
32. Working steam pressure: 5 Bar
33. Temperature control:

RTD, controlled in 2-can groups
34. Drying section drive system:

Tension controlled by load cell ( $\pm 1.0 \mathrm{GPE}$ )
35. Stretch:

Monitored (within $0.01 \%$ stretch)
36. Drive type:

Self-lub chain (final stack only)
37. Over-oiler/waxer:

Steam heated
38. Hood:

Buyer to arrange hood locally as per UKIL design
39. Exhaust fans:
$16,000 \mathrm{~m} 3 / \mathrm{hr}$. per fan

## HEAD END

## 40. Winding head type:

Conventional
41. Loom beam width:
$2,200 \mathrm{~mm}$ to $5,400 \mathrm{~mm}$
42. Loom beam diameter:
$1,000 \mathrm{~mm}, 1,100 \mathrm{~mm}, 1,250 \mathrm{~mm}, 1,400 \mathrm{~mm}$
43. Maximum mechanical speed:
150 MPM
44. Maximum winding tension: 900 Kg
45. Tension control: by load cell ( $\pm 1.0 \mathrm{GPE}$ )
46. Stretch

Monitored (within 0.01 stretch)
47. Delivery roll (urethane covered):
$260 \mathrm{~mm} \varnothing$ working width +200 mm
48. Nip roll/load cell roll:
$160 \mathrm{~mm} \varnothing$ working width +200 mm
49. Doffing: Hydraulic operation $3,200 \mathrm{~kg}$ max. capacity
50. Dual Press Roll Assembly: pneumatically controlled 100kg - 600kg
51. Comb:

Zig Zag, motorized movement
52. Taping device

Motorized movement
53. Final moisture (full width of sheet): Resistive rod sensor

## DRIVE AND CONTROL SYSTEM

54. Human Machine Interface (HMI):

480 mm color touchscreen utilizing MS Visual Basic
55. PC based:

2Gb Compact Flash card stores all programs/style information, reliable diskless technology
56. Maximum ambient operating temp:
$50^{\circ} \mathrm{C}, \mathrm{AC}$ unit is required for higher temperatures
57. Operating system (embedded):

Microsoft Windows 7 with real time extension
58. Control software:

IEC 61131-3 compliant
59. Style recipe storage:

Up to 999 styles
60. Communication:

High speed Ethercat to drives and I/O
61. Drives:

Yaskawa A1000 AC Vector/Servo
62. I/O:

Beckhoff Ethercat distributed I/O with direct strain gauge interface, RTD, current, voltage, relay, etc. mounted close to the device for easy installation and troubleshooting
63. Motors:

SEW with encoder feedback for speed control
64. Control cabinets:

3C labeling on all wiring

